

Handbook Of Hybrid Systems Control Theory Tools Applications

Hybrid System Identification helps readers to build mathematical models of dynamical systems switching between different operating modes, from their experimental observations. It provides an overview of the interaction between system identification, machine learning and pattern recognition fields in explaining and analysing hybrid system identification. It emphasises the optimization and computational complexity issues that lie at the core of the problems considered and sets them aside from standard system identification problems. The book presents practical methods that leverage this complexity, as well as a broad view of state-of-the-art machine learning methods. The authors illustrate the key technical points using examples and figures to help the reader understand the material. The book includes an in-depth discussion and computational analysis of hybrid system identification problems, moving from the basic questions of the definition of hybrid systems and system identification to methods of hybrid system identification and the estimation of switched linear/affine and piecewise affine models. The authors also give an overview of the various applications of hybrid systems, discuss the connections to other fields, and describe more advanced material on recursive, state-space and nonlinear hybrid system identification. Hybrid System Identification includes a detailed exposition of major methods, which allows researchers and practitioners to acquaint themselves rapidly with state-of-the-art tools. The book is also a sound basis for graduate and undergraduate students studying this area of control, as the presentation and form of the book provides the background and coverage necessary for a full understanding of hybrid system identification, whether the reader is initially familiar with system identification related to hybrid systems or not.

This book assembles new methods showing the automotive engineer for the first time how hybrid vehicle configurations can be modeled as systems with discrete and continuous controls. These hybrid systems describe naturally and compactly the networks of embedded systems which use elements such as integrators, hysteresis, state-machines and logical rules to describe the evolution of continuous and discrete dynamics and arise inevitably when modeling hybrid electric vehicles. They can throw light on systems which may otherwise be too complex or recondite. Hybrid Systems, Optimal Control and Hybrid Vehicles shows the reader how to formulate and solve control problems which satisfy multiple objectives which may be arbitrary and complex with contradictory influences on fuel consumption, emissions and drivability. The text introduces industrial engineers, postgraduates and researchers to the theory of hybrid optimal control problems. A series of novel algorithmic developments provides tools for solving engineering problems of growing complexity in the field of hybrid vehicles. Important topics of real relevance rarely found in text books and research publications—switching costs, sensitivity of discrete decisions and their impact on fuel savings, etc.—are discussed and supported with practical applications. These demonstrate the contribution of optimal hybrid control in predictive energy management, advanced powertrain calibration, and the optimization of vehicle configuration with respect to fuel economy, lowest emissions and smoothest drivability. Numerical issues such as computing resources, simplifications and stability are treated to enable readers to assess such complex systems. To help industrial engineers and managers with project decision-making, solutions for many important problems in hybrid vehicle control are provided in terms of requirements, benefits and risks. A graduate-level textbook, Hybrid Dynamical Systems provides an accessible and comprehensive introduction to the theory of hybrid systems. It emphasizes results that are central to a good understanding of the importance and role of such systems. The authors have developed the materials in this book while teaching courses on hybrid systems, cyber-physical systems, and formal methods. This textbook helps students to become familiar with both the major approaches coloring the study of hybrid dynamical systems. The computer science and control systems points of view – emphasizing discrete dynamics and real time, and continuous dynamics with switching, respectively – are each covered in detail. The book shows how the behavior of a system with tightly coupled cyber- (discrete) and physical (continuous) elements can best be understood by a model simultaneously encompassing all the dynamics and their interconnections. The theory presented is of fundamental importance in a wide range of emerging fields from next-generation transportation systems to smart manufacturing. Features of the text include: extensive use of examples to illustrate the main concepts and to provide insights additional to those acquired from the main text; chapter summaries enabling students to assess their progress; end-of-chapter exercises, which test learning as a course proceeds; an instructor's guide showing how different parts of the book can be exploited for different course requirements; and a solutions manual, freely available for download by instructors adopting the book for their teaching. Access to MATLAB and Stateflow is not required but would be beneficial, especially for exercises in which simulations are a key tool.

A compendium of the authors' recently published results, this book discusses sliding mode control of uncertain nonlinear systems, with a particular emphasis on advanced and optimization based algorithms. The authors survey classical sliding mode control theory and introduce four new methods of advanced sliding mode control. They analyze classical theory and advanced algorithms, with numerical results complementing the theoretical treatment. Case studies examine applications of the algorithms to complex robotics and power grid problems. Advanced and Optimization Based Sliding Mode Control: Theory and Applications is the first book to systematize the theory of optimization based higher order sliding mode control and illustrate advanced algorithms and their applications to real problems. It presents systematic treatment of event-triggered and model based event-triggered sliding mode control schemes, including schemes in combination with model predictive control, and presents adaptive algorithms as well as algorithms capable of dealing with state and input constraints. Additionally, the book includes simulations and experimental results obtained by applying the presented control strategies to real complex systems. This book is suitable for students and researchers interested in control theory. It will also be attractive to practitioners interested in implementing the

illustrated strategies. It is accessible to anyone with a basic knowledge of control engineering, process physics, and applied mathematics.

This review volume reports the state-of-the-art in Linear Parameter Varying (LPV) system identification. It focuses on the most recent LPV identification methods for both discrete-time and continuous-time models--

At publication, The Control Handbook immediately became the definitive resource that engineers working with modern control systems required. Among its many accolades, that first edition was cited by the AAP as the Best Engineering Handbook of 1996. Now, 15 years later, William Levine has once again compiled the most comprehensive and authoritative resource on control engineering. He has fully reorganized the text to reflect the technical advances achieved since the last edition and has expanded its contents to include the multidisciplinary perspective that is making control engineering a critical component in so many fields. Now expanded from one to three volumes, The Control Handbook, Second Edition organizes cutting-edge contributions from more than 200 leading experts. The third volume, Control System Advanced Methods, includes design and analysis methods for MIMO linear and LTI systems, Kalman filters and observers, hybrid systems, and nonlinear systems. It also covers advanced considerations regarding — Stability Adaptive controls System identification Stochastic control Control of distributed parameter systems Networks and networked controls As with the first edition, the new edition not only stands as a record of accomplishment in control engineering but provides researchers with the means to make further advances. Progressively organized, the first two volumes in the set include: Control System Fundamentals Control System Applications

Control of Discrete-event Systems provides a survey of the most important topics in the discrete-event systems theory with particular focus on finite-state automata, Petri nets and max-plus algebra. Coverage ranges from introductory material on the basic notions and definitions of discrete-event systems to more recent results. Special attention is given to results on supervisory control, state estimation and fault diagnosis of both centralized and distributed/decentralized systems developed in the framework of the Distributed Supervisory Control of Large Plants (DISC) project. Later parts of the text are devoted to the study of congested systems through fluidization, an over approximation allowing a much more efficient study of observation and control problems of timed Petri nets. Finally, the max-plus algebraic approach to the analysis and control of choice-free systems is also considered. Control of Discrete-event Systems provides an introduction to discrete-event systems for readers that are not familiar with this class of systems, but also provides an introduction to research problems and open issues of current interest to readers already familiar with them. Most of the material in this book has been presented during a Ph.D. school held in Cagliari, Italy, in June 2011.

Transportation Cyber-Physical Systems provides current and future researchers, developers and practitioners with the latest thinking on the emerging interdisciplinary field of Transportation Cyber Physical Systems (TCPS). The book focuses on enhancing efficiency, reducing environmental stress, and meeting societal demands across the continually growing air, water and land transportation needs of both people and goods. Users will find a valuable resource that helps accelerate the research and development of transportation and mobility CPS-driven innovation for the security, reliability and stability of society at-large. The book integrates ideas from Transport and CPS experts and visionaries, consolidating the latest thinking on the topic. As cars, traffic lights and the built environment are becoming connected and augmented with embedded intelligence, it is important to understand how smart ecosystems that encompass hardware, software, and physical components can help sense the changing state of the real world. Bridges the gap between the transportation, CPS and civil engineering communities Includes numerous examples of practical applications that show how diverse technologies and topics are integrated in practice Examines timely, state-of-the-art topics, such as big data analytics, privacy, cybersecurity and smart cities Shows how TCPS can be developed and deployed, along with its associated challenges Includes pedagogical aids, such as Illustrations of application scenarios, architecture details, tables describing available methods and tools, chapter objectives, and a glossary Contains international contributions from academia, government and industry

This book constitutes the thoroughly refereed proceedings of the 20th International Symposium on Static Analysis, SAS 2013, held in Seattle, WA, USA, in June 2013. The 23 revised full papers presented together with 2 invited talks were selected from 56 submissions. The papers address all aspects of static analysis, including abstract domains, abstract interpretation, abstract testing, bug detection, data flow analysis, model checking, new applications, program transformation, program verification, security analysis, theoretical frameworks, and type checking.

This book presents theory and latest application work in Bond Graph methodology with a focus on: • Hybrid dynamical system models, • Model-based fault diagnosis, model-based fault tolerant control, fault prognosis • and also addresses • Open thermodynamic systems with compressible fluid flow, • Distributed parameter models of mechanical subsystems. In addition, the book covers various applications of current interest ranging from motorised wheelchairs, in-vivo surgery robots, walking machines to wind-turbines. The up-to-date presentation has been made possible by experts who are active members of the worldwide bond graph modelling community. This book is the completely revised 2nd edition of the 2011 Springer compilation text titled Bond Graph Modelling of Engineering Systems – Theory, Applications and Software Support. It extends the presentation of theory and applications of graph methodology by new developments and latest research results. Like the first edition, this book addresses readers in academia as well as practitioners in industry and invites experts in related fields to consider the potential and the state-of-the-art of bond graph modelling.

This handbook presents state-of-the-art research in reinforcement learning, focusing on its applications in the control and game theory of dynamic systems and future directions for related research and technology. The contributions gathered in this book deal with challenges faced when using learning and adaptation methods to solve academic and industrial problems, such as optimization in dynamic environments with single and multiple agents, convergence and performance analysis, and online implementation. They explore means by which these difficulties can be solved, and cover a wide range of related topics including: deep learning; artificial intelligence; applications of game theory; mixed modality learning; and multi-agent reinforcement learning. Practicing engineers and scholars in the field of machine learning, game theory, and autonomous control will find the Handbook of Reinforcement Learning and Control to be thought-provoking, instructive and informative. .

New Trends in Observer-Based Control: An Introduction to Design Approaches and Engineering Applications, Volume One presents a clear-and-concise introduction to the latest advances in observer-based

control design. It provides a comprehensive tutorial on new trends in the design of observer-based controllers for which the separation principle is well established. In addition, since the theoretical developments remain more advanced than the engineering applications, more experimental results are still needed. A wide range of applications are covered, and the book contains worked examples which make it ideal for both advanced courses and researchers starting in the field. Presents a clear-and-concise introduction to the latest advances in observer-based control design Offers concise content on the many facets of observer-based control design Discusses key applications in the fields of power systems, robotics and mechatronics, and flight and automotive systems

This monograph introduces a newly developed robust-control design technique for a wide class of continuous-time dynamical systems called the "attractive ellipsoid method." Along with a coherent introduction to the proposed control design and related topics, the monograph studies nonlinear affine control systems in the presence of uncertainty and presents a constructive and easily implementable control strategy that guarantees certain stability properties. The authors discuss linear-style feedback control synthesis in the context of the above-mentioned systems. The development and physical implementation of high-performance robust-feedback controllers that work in the absence of complete information is addressed, with numerous examples to illustrate how to apply the attractive ellipsoid method to mechanical and electromechanical systems. While theorems are proved systematically, the emphasis is on understanding and applying the theory to real-world situations. Attractive Ellipsoids in Robust Control will appeal to undergraduate and graduate students with a background in modern systems theory as well as researchers in the fields of control engineering and applied mathematics.

This thesis addresses optimal control of discrete-time switched linear systems with application to networked embedded control systems (NECSs). Part I focuses on optimal control and scheduling of discrete-time switched linear systems. The objective is to simultaneously design a control law and a switching (scheduling) law such that a cost function is minimized. This optimization problem exhibits exponential complexity. Taming the complexity is a major challenge. Two novel methods are presented to approach this optimization problem: Receding-horizon control and scheduling relies on the receding horizon principle. The optimization problem is solved based on relaxed dynamic programming, allowing to reduce complexity by relaxing optimality within predefined bounds. The solution can be expressed as a piecewise linear (PWL) state feedback control law. Stability is addressed via an a priori stability condition based on a terminal weighting matrix and several a posteriori stability criteria based on constructing piecewise quadratic Lyapunov functions and on utilizing the cost function as a candidate Lyapunov function. Moreover, a region-reachability criterion is derived. Periodic control and scheduling relies on periodic control theory. Both offline and online scheduling are studied. The optimization problem is solved based on periodic control and exhaustive search. The online scheduling solution can again be expressed as a PWL state feedback control law. Stability is guaranteed inherently. Several methods are proposed to reduce the online complexity based on relaxation and heuristics. Part II focuses on optimal control and scheduling of NECSs. The NECS is modeled as a block-diagonal discrete-time switched linear system. Various control and scheduling codesign strategies are derived based on the methods from Part I regarding the structural properties of NECSs. The methods presented in Part I and II are finally evaluated in a case study.

This research monograph summarizes solutions to reconfigurable fault-tolerant control problems for nonlinear dynamical systems that are based on the fault-hiding principle. It emphasizes but is not limited to complete actuator and sensor failures. In the first part, the monograph starts with a broad introduction of the control reconfiguration problems and objectives as well as summaries and explanations of solutions for linear dynamical systems. The solution is always a reconfiguration block, which consists of linear virtual actuators in the case of actuator faults and linear virtual sensors in the case of sensor faults. The main advantage of the fault-hiding concept is the reusability of the nominal controller, which remains in the loop as an active system while the virtual actuator and sensor adapt the control input and the measured output to the fault scenario. The second and third parts extend virtual actuators and virtual sensors towards the classes of Hammerstein-Wiener systems and piecewise affine systems. The main analyses concern stability recovery, setpoint tracking recovery, and performance recovery as reconfiguration objectives. The fourth part concludes the monograph with descriptions of practical implementations and case studies. The book is primarily intended for active researchers and practicing engineers in the field of fault-tolerant control. Due to many running examples it is also suitable for interested graduate students.

This volume is based on the proceedings of the 28th International Conference on CAD/CAM, Robotics and Factories of the Future. This book specially focuses on the positive changes made in the field of robotics, CAD/CAM and future outlook for emerging manufacturing units. Some of the important topics discussed in the conference are product development and sustainability, modeling and simulation, automation, robotics and handling systems, supply chain management and logistics, advanced manufacturing processes, human aspects in engineering activities, emerging scenarios in engineering education and training. The contents of this set of proceedings will prove useful to both researchers and practitioners.

This book constitutes the proceedings of the 11th International Conference on Quantitative Evaluation of Systems, QEST 2014, held in Florence, Italy, in September 2014. The 24 full papers and 5 short papers included in this volume were carefully reviewed and selected from 61 submissions. They are organized in topical sections named: Kronecker and product form methods; hybrid systems; mean field/population analysis; models and tools; simulation; queueing, debugging and tools; process algebra and equivalences; automata and Markov process theory; applications, theory and tools; and probabilistic model checking.

This book constitutes the proceedings of the 6th International Workshop on Design, Modeling, and Evaluation of Cyber Physical Systems, CyPhy2016, held in conjunction with ESWeek 2016, in Pittsburgh, PA, USA, in October 2016. The 9 papers presented in this volume were carefully reviewed and selected from 14 submissions. They broadly interpret, from a diverse set of disciplines, the modeling, simulation, and evaluation of cyber-physical systems with a particular focus on techniques and components to enable and support virtual prototyping and testing.

Communications and Controls in Cyber Physical Systems: Theory, Design and Applications in Smart Grids provides readers with all they need to know about cyber physical systems (CPSs), such as smart grids, which have attracted intensive studies in recent years. Communications and controls are of key importance for maintaining and stabilizing the operation of the physical dynamics in these complicated systems. This book presents a systematic treatment on the communication and control aspects of CPSs, along with applications to the smart grid in four parts, including the basics of CPS, communications and controls, an explanation of the integration with CPS, coverage of controls with information constraints in CPS, and an applications oriented focus on smart grids as a CPS. Drawing upon years of practical experience and using numerous examples and illustrations, the authors' discuss key communication and controls design methods that can be integrated into a CPS, how communication and control schemes can be applied in practical systems such as smart grids, new directions and approaches for traditional engineers and researchers in communications, and controls and power systems as they relates to CPSs. Presents a systematic treatment on the communication and control aspects of cyber physical systems (CPSs) Discusses key communication and controls design methods that can be integrated into a CPS Demonstrates how communication and control schemes can be applied in practical systems such as smart grids Includes new directions and approaches for traditional engineers and researchers in communications, controls, and power systems as they relate to CPSs

The series *Advances in Industrial Control* aims to report and encourage technology transfer in control engineering. The rapid development of control technology has an impact on all areas of the control discipline. New theory, new controllers, actuators, sensors, new industrial processes, computer methods, new applications, new philosophies ..., new challenges. Much of this development work resides in industrial reports, feasibility study papers and the reports of advanced collaborative projects. The series offers an opportunity for researchers to present an extended exposition of such new work in all aspects of industrial control for wider and rapid dissemination. The water and wastewater industry has undergone many changes in recent years. Of particular importance has been a renewed emphasis on improving resource management with tighter regulatory controls setting new targets on pricing, industry efficiency and loss reduction for both water and wastewater with more stringent environmental discharge conditions for wastewater. Meantime, the demand for water and wastewater services grows as the population increases and wishes for improved living conditions involving, among other items, domestic appliances that use water. Consequently, the installed infrastructure of the industry has to be continuously upgraded and extended, and employed more effectively to accommodate the new demands, both in throughput and in meeting the new regulatory conditions. Investment in fixed infrastructure is capital-intensive and slow to come on-stream. One outcome of these changes and demands is that the industry is examining the potential benefits of, and in many cases using, more advanced control systems.

Despite the length of time it has been around, its importance, and vast amounts of research, combustion is still far from being completely understood. Issues regarding the environment, cost, and fuel consumption add further complexity, particularly in the process and power generation industries. Dedicated to advancing the art and science of industry, *The Mechanical Systems Design Handbook: Modeling, Measurement, and Control* presents a practical overview of basic issues associated with design and control of mechanical systems. In four sections, each edited by a renowned expert, this book answers diverse questions fundamental to the successful design and implementation of mechanical systems in a variety of applications. Manufacturing addresses design and control issues related to manufacturing systems. From fundamental design principles to control of discrete events, machine tools, and machining operations to polymer processing and precision manufacturing systems. Vibration Control explores a range of topics related to active vibration control, including piezoelectric networks, the boundary control method, and semi-active suspension systems. Aerospace Systems presents a detailed analysis of the mechanics and dynamics of tensegrity structures Robotics offers encyclopedic coverage of the control and design of robotic systems, including kinematics, dynamics, soft-computing techniques, and teleoperation. Mechanical systems designers and engineers have few resources dedicated to their particular and often unique problems. *The Mechanical Systems Design Handbook* clearly shows how theory applies to real world challenges and will be a welcomed and valuable addition to your library.

For many years technical and medical diagnostics has been the area of intensive scientific research. It covers well-established topics as well as emerging developments in control engineering, artificial intelligence, applied mathematics, pattern recognition and statistics. At the same time, a growing number of applications of different fault diagnosis methods, especially in electrical, mechanical, chemical and medical engineering, is being observed. This monograph contains a collection of 44 carefully selected papers contributed by experts in technical and medical diagnostics, and constitutes a comprehensive study of the field. The aim of the book is to show the bridge between technical and medical diagnostics based on artificial intelligence methods and techniques. It is divided into four parts: I. Soft Computing in Technical Diagnostics, II. Medical Diagnostics and Biometrics, III. Robotics and Computer Vision, IV. Various Problems of Technical Diagnostics. The monograph will be of interest to scientists as well as academics dealing with the problems of designing technical and medical diagnosis systems. Its target readers are also junior researchers and students of computer science, artificial intelligence, control or robotics.

Setting out core theory and reviewing a range of new methods, theoretical problems and applications, this handbook shows how hybrid dynamical systems can be modelled and understood. Sixty expert authors involved in the recent research activities and industrial application studies provide practical insights on topics ranging from the theoretical investigations over computer-aided design to applications in energy management and the process industry. Structured into three parts, the book opens with a thorough introduction to hybrid systems theory, illustrating new dynamical phenomena through numerous examples. Part II then provides a survey of key tools and tool integration activities. Finally, Part III is dedicated to applications, implementation issues and system integration, considering different domains such as industrial control, automotive systems and digital networks. Three running examples are referred to throughout the book, together with numerous illustrations, helping both researchers and industry professionals to understand complex theory, recognise problems and find appropriate solutions.

Cyber-physical systems play a crucial role in connecting aspects of online life to physical life. By studying emerging trends in these systems, programming techniques can be optimized and strengthened to create a higher level of effectiveness. *Solutions for Cyber-Physical Systems Ubiquity* is a critical reference source that discusses the issues and challenges facing the implementation, usage, and challenges of cyber-physical systems. Highlighting relevant topics such as the Internet of Things, smart-card security, multi-core environments, and wireless sensor nodes, this scholarly publication is ideal for engineers, academicians, computer science students, and researchers that would like to stay abreast of current methodologies and trends involving cyber-physical system progression.

The three-volume set LNCS 12476 - 12478 constitutes the refereed proceedings of the 9th International Symposium on Leveraging Applications of Formal Methods, ISoLA 2020, which was planned to take place during October 20–30, 2020, on Rhodes, Greece. The event itself was postponed to 2021 due to the COVID-19 pandemic. The papers presented were carefully reviewed and selected for inclusion in the proceedings. Each volume focusses on an individual topic with topical section headings within the volume: Part I, Verification Principles: Modularity and (De-)Composition in Verification; X-by-Construction: Correctness meets Probability; 30 Years of Statistical Model Checking; Verification and Validation of Concurrent and Distributed Systems. Part II, Engineering Principles: Automating Software Re-Engineering; Rigorous Engineering of Collective Adaptive Systems. Part III, Applications: Reliable Smart Contracts: State-of-the-art, Applications, Challenges and Future Directions; Automated Verification of Embedded Control Software; Formal methods for DIStributed COmputing in future RAILway systems.

This book presents bond graph model-based fault detection with a focus on hybrid system models. The book addresses model design, simulation, control and model-based fault diagnosis of multidisciplinary engineering systems. The text begins with a brief survey of the state-of-the-art, then focuses on hybrid systems. The author then uses different bond graph approaches throughout the text and provides case studies.

This book presents the state of the art in the relatively new field of dynamic economic modelling with regime switches. The contributions, written by prominent scholars in the field, focus on dynamic decision

problems with regime changes in underlying dynamics or objectives. Such changes can be externally driven or internally induced by decisions. Utilising the most advanced mathematical methods in optimal control and dynamic game theory, the authors address a broad range of topics, including capital accumulation, innovations, financial decisions, population economics, environmental and resource economics, institutional change and the dynamics of addiction. Given its scope, the book will appeal to all scholars interested in mathematical and quantitative economics.

This book constitutes the refereed proceedings of the 8th International Joint Conference on Automated Reasoning, IJCAR 2016, held in Coimbra, Portugal, in June/July 2016. IJCAR 2014 was a merger of three leading events in automated reasoning, namely CADE (International Conference on Automated Deduction), FroCoS (International Symposium on Frontiers of Combining Systems) and TABLEAUX (International Conference on Automated Reasoning with Analytic Tableaux and Related Methods). The 26 revised full research papers and 9 system descriptions presented together with 4 invited talks were carefully reviewed and selected from 79 submissions. The papers have been organized in topical sections on satisfiability of Boolean formulas, satisfiability modulo theory, rewriting, arithmetic reasoning and mechanizing mathematics, first-order logic and proof theory, first-order theorem proving, higher-order theorem proving, modal and temporal logics, non-classical logics, and verification.

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This book constitutes the thoroughly refereed post-conference proceedings of the Third International Conference on Game Theory for Networks (GameNets 2012) held in Vancouver, Canada, May 24-26, 2012. The 13 revised full papers were carefully selected from 24 submissions and are presented together with 7 invited papers. The papers focus on topics such as mechanism design, physical layer games, network mechanisms, stochastic and dynamic games, game-theoretic network models, cooperative games in networks, security games, spectrum sharing games, P2P and social networks and economics of network QoS.

The book discusses essential topics in industrial and applied mathematics such as image processing with a special focus on medical imaging, biometrics and tomography. Applications of mathematical concepts to areas like national security, homeland security and law enforcement, enterprise and e-government services, personal information and business transactions, and brain-like computers are also highlighted. These contributions – all prepared by respected academicians, scientists and researchers from across the globe – are based on papers presented at the international conference organized on the occasion of the Silver Jubilee of the Indian Society of Industrial and Applied Mathematics (ISIAM) held from 29 to 31 January 2016 at Sharda University, Greater Noida, India. The book will help young scientists and engineers grasp systematic developments in those areas of mathematics that are essential to properly understand challenging contemporary problems.

This book constitutes the refereed proceedings of the 6th International Symposium on NASA Formal Methods, NFM 2014, held in Houston, TX, USA, April 29 – May 1, 2014. The 20 revised regular papers presented together with 9 short papers were carefully reviewed and selected from 107 submissions. The topics include model checking, theorem proving, static analysis, model-based development, runtime monitoring, formal approaches to fault tolerance, applications of formal methods to aerospace systems, formal analysis of cyber-physical systems, including hybrid and embedded systems, formal methods in systems engineering, modeling, requirements and specifications, requirements generation, specification debugging, formal validation of specifications, use of formal methods in safety cases, use of formal methods in human-machine interaction analysis, formal methods for parallel hardware implementations, use of formal methods in automated software engineering and testing, correct-by-design, design for verification, and property based design techniques, techniques and algorithms for scaling formal methods, e.g., abstraction and symbolic methods, compositional techniques, parallel and distributed techniques, and application of formal methods to emerging technologies.

Winner of Choice Magazine - Outstanding Academic Titles for 2007 Buildings account for over one third of global energy use and associated greenhouse gas emissions worldwide. Reducing energy use by buildings is therefore an essential part of any strategy to reduce greenhouse gas emissions, and thereby lessen the likelihood of potentially catastrophic climate change.

Bringing together a wealth of hard-to-obtain information on energy use and energy efficiency in buildings at a level which can be easily digested and applied, Danny Harvey offers a comprehensive, objective and critical sourcebook on low-energy buildings. Topics covered include: thermal envelopes, heating, cooling, heat pumps, HVAC systems, hot water, lighting, solar energy, appliances and office equipment, embodied energy, buildings as systems and community-integrated energy systems (cogeneration, district heating, and district cooling). The book includes exemplary buildings and techniques from North America, Europe and Asia, and combines a broad, holistic perspective with technical detail in an accessible and insightful manner.

The vast majority of control systems built today are embedded; that is, they rely on built-in, special-purpose digital computers to close their feedback loops. Embedded systems are common in aircraft, factories, chemical processing plants, and even in cars—a single high-end automobile may contain over eighty different computers. The design of embedded controllers and of the intricate, automated communication networks that support them raises many new questions—practical, as well as theoretical—about network protocols, compatibility of operating systems, and ways to maximize the effectiveness of the embedded hardware. This handbook, the first of its kind, provides engineers, computer scientists, mathematicians, and students a broad, comprehensive source of information and technology to address many questions and aspects of embedded and networked control. Separated into six main sections—Fundamentals, Hardware, Software, Theory, Networking, and Applications—this work unifies into a single reference many scattered articles, websites, and specification sheets. Also included are case studies, experiments, and examples that give a multifaceted view of the subject, encompassing computation and communication considerations.

This book constitutes the refereed proceedings of the 13th International Conference on Integrated Formal Methods, IFM 2017, held in Turin, Italy, in September 2017. The 24 full papers and 4 short papers presented were carefully reviewed and selected from 61 submissions. They are organized in topical sections on cyber-physical systems, software verification tools, safety-critical

systems, concurrency and distributed systems, program verification techniques, formal modeling, and verified software..

In addition to explaining and modeling unexplored phenomena in nature and society, chaos uses vital parts of nonlinear dynamical systems theory and established chaotic theory to open new frontiers and fields of study. Handbook of Applications of Chaos Theory covers the main parts of chaos theory along with various applications to diverse areas. Expert contributors from around the world show how chaos theory is used to model unexplored cases and stimulate new applications. Accessible to scientists, engineers, and practitioners in a variety of fields, the book discusses the intermittency route to chaos, evolutionary dynamics and deterministic chaos, and the transition to phase synchronization chaos. It presents important contributions on strange attractors, self-exciting and hidden attractors, stability theory, Lyapunov exponents, and chaotic analysis. It explores the state of the art of chaos in plasma physics, plasma harmonics, and overtone coupling. It also describes flows and turbulence, chaotic interference versus decoherence, and an application of microwave networks to the simulation of quantum graphs. The book proceeds to give a detailed presentation of the chaotic, rogue, and noisy optical dissipative solitons; parhelic-like circle and chaotic light scattering; and interesting forms of the hyperbolic prism, the Poincaré disc, and foams. It also covers numerous application areas, from the analysis of blood pressure data and clinical digital pathology to chaotic pattern recognition to economics to musical arts and research.

This open access book constitutes the proceedings of the 23rd International Conference on Fundamental Approaches to Software Engineering, FASE 2020, which took place in Dublin, Ireland, in April 2020, and was held as Part of the European Joint Conferences on Theory and Practice of Software, ETAPS 2020. The 23 full papers, 1 tool paper and 6 testing competition papers presented in this volume were carefully reviewed and selected from 81 submissions. The papers cover topics such as requirements engineering, software architectures, specification, software quality, validation, verification of functional and non-functional properties, model-driven development and model transformation, software processes, security and software evolution.

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